

A-scans per B-scan and the number of B-scans per volume. After acquisition, the whole volume can be stored for posterior analysis or discarded.

B. Software

A customizable software was developed using object-oriented programming (Microsoft Visual C++/IDE) for the 64-bit Microsoft Windows 7 operating system resorting to libraries from Innovative to deal with data acquisition and hardware control.

To perform B- and volume scans, the laser beam must be swept, respectively, along one (X) and two (X-Y) axes by means of a Dual-Axis Scanning Galvo System GVS002 (Thorlabs GmbH, Munich, Germany) controlled by one of the D/A channels, up to a maximum scan angle of 20° in both directions. With the current hardware implementation, 1510 data points are digitalized in 10 μs, which correspond to the number of sample wavelengths outputted by the laser source. This frequency sweep corresponds to the entire A-scan which can be computed owing to the Fourier transform. The number of useful data points is, nevertheless, restricted to 1376, with the remaining ones produced by the dummy clock outputted by the laser source.

The number of A-scans per B-scan and the number of B-scans per volume are only limited by the resolution of the step increments of the galvo system and/or by the acquisition time.

Synchronization between the acquisition and laser emission is paramount for SS-OCT. As such, embedded in the laser source is a Mach-Zehnder interferometer (MZI) to provide the optical clock signal. It allows to sample evenly spaced frequencies even though the output is linearly swept in wavelength (k-space). This signal presents maxima and minima equally spaced in the optical frequency domain (k-space). The difference between two maxima is defined by the free spectral range of MZI. Linearized fringe signals with equal k-spacing can be achieved by clocking the high-speed A/D channel of the acquisition board with the clock provided by the source. The Fourier transform analysis can thus be directly applied on the acquired data. Moreover, the laser source also provides a trigger signal which is connected to the SYNC port of the acquisition board. This signal is responsible for starting the I/O module.

C. Results

The performance of the system was established based on commonly found parameters on the literature [6][7]: sensitivity (S), dynamic range (DR), axial resolution (AR) and depth sensitivity roll-off. Sensitivity is related with the smallest reflectivity, $R_{s,min}$, that can be detected, defined as the signal level when $SNR=1$.

$$S_{dB} = 10 \log_{10} \frac{R_s}{R_{s,min}} \quad (1)$$

One way of experimentally measure S is to use a gold mirror ($R_s=1$). Thus, (1) becomes:

$$S_{dB} = 10 \log_{10} \frac{1}{R_{s,min}} \quad (2)$$

The sensitivity of the system can be estimated from the ratio between the output from the optimal reflector (the system point spread function, PSF) and that from the noise (no sample), the latter being defined as the standard deviation of the readings, leading to:

$$S_{dB} = 20 \log_{10} \frac{PSF_{peak}}{\sigma_{noise}} \quad (3)$$

In these conditions, a sensitivity of 105 dB was experimentally determined, allowing to calculate $R_{s,min}$ from (2).

DR regards to the ratio between the maximum and the minimum reflectivity signal that can be measured within the same A-scan. As such, a DR of 60 dB was found for the current setup.

The theoretical value of the axial resolution, in the air and assuming a Gaussian laser beam power spectrum, is given by

$$\Delta z = \frac{2 \ln(2) \lambda_0^2}{\pi \Delta \lambda} = 4.51 \mu m \quad (4)$$

The experimentally determined value, using a gold mirror, is 8.1 μm, though.

Finally, the sensitivity roll-off with depth was assessed over an axial range of 4 mm to find it to be less than 1 dB/mm in the first 2.8 mm and about 3 dB/mm thereafter.

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